



Three Dimensional Trans-Sasakian Manifold Admitting Quarter Symmetric Metric Connection

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Abstract

The object of this paper is to study quarter-symmetric metric connection on a trans-Sasakian manifold. Here we study locally ϕ -symmetric, ϕ -symmetric and concircular ϕ -symmetric trans-Sasakian manifold with respect to quarter symmetric metric connection and obtained some interesting results.

Keywords: Quarter symmetric metric connection, Trans-Sasakian manifold, ϕ -symmetry.

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1 Introduction

In 1985, Oubina J. A. [1] introduced a new class of almost Contact manifold namely trans-Sasakian manifold. Many geometers like [2], [3], [4], [5], [6], [7], [8], [9] have studied this manifold and obtained many interesting results. The notion of quarter-symmetric connection generalizes the semi-symmetric connection. In 1924, Friedman A. and Schouten J. A. [10], [11] introduced the notion of semi-symmetric linear connection on a differentiable manifold. In 1975, Golab S. [12] defined and studied

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quarter-symmetric connection in a differentiable manifold with affine connection. Rastogi S. C. [13], [14] continued the systematic study of quarter symmetric metric connection.

A linear connection $\tilde{\nabla}$ in $(2n + 1)$ dimensional differentiable manifold is said to be a quarter symmetric connection if its torsion tensor T is of the form

$$T(X, Y) = \tilde{\nabla}_X Y - \tilde{\nabla}_Y X - [X, Y], \quad (1.1)$$

$$= \eta(Y)\phi X - \eta(X)\phi Y, \quad (1.2)$$

where η is a 1-form and ϕ is a tensor of type $(1, 1)$. In particular, if $\phi X = X$, then the quarter-symmetric connection reduces to the semi-symmetric connection. And if quarter-symmetric metric connection $\tilde{\nabla}$ satisfies the condition

$$(\tilde{\nabla}_X g)(Y, Z) = 0,$$

for all $X, Y, Z \in \chi(M)$, where $\chi(M)$ is the Lie algebra of vector fields on the manifold M , then $\tilde{\nabla}$ is said to be a quarter symmetric metric connection.

In 1980, Mishra R. S. and Pandey S. N. [15] studied quarter symmetric metric connection in a Riemannian, Kaehlerian and Sasakian manifolds. In 1982, Yano K. and Imai T. [16] studied quarter symmetric metric connection in Hermitian and Kaehlerian manifolds. In 1991, Mukhopadhyay S. et al. [17] studied quarter symmetric metric connection on a Riemannian manifold with an almost complex structure ϕ . Quarter symmetric metric connection was also studied by Singh R. N. [18]. Biswas and De U. C. [19], De U. C. and Mondal A. K. [20] studied Quarter symmetric metric connection on SP-Sasakian manifold and Sasakian manifolds. Pradeep Kumar K. T., Bagewadi C. S. and Venkatesha [21,22] and Prakasha D. G. [23] studied Quarter symmetric metric connection on K-contact manifolds and Kenmotsu manifolds. Shyamal Kumar Hui [24] studied ϕ -pseudo symmetric Kenmotsu manifolds with respect to quarter symmetric metric connection. Also Patra C. and Bhatt-acharya A. [25] studied trans-Sasakian manifold admitting quarter symmetric non-metric connection.

The notion of local symmetric of a Riemannian manifold has been weakened by many authors in several ways to a different extent. As a weaker version of local symmetric, Takahashi T. [26] introduced the notion of locally ϕ -symmetry on a Sasakian manifold. In the context of Contact geometry the notion of ϕ -symmetric is introduced and studied by Boeckx E. Buecken P. and Vanhecke L. [27] with several examples. Motivated by these ideas, in the present paper we like to study quarter symmetric metric connection on a trans-Sasakian manifold. The present paper is organized as follows.

In section 2, we recall some preliminary results. In section 3, we give the relation between the Levi-Civita connection and the quarter symmetric metric connection on three dimensional trans-Sasakian manifold. Section 4 deals with locally ϕ -symmetric trans-Sasakian manifold with respect to quarter symmetric metric connection. In the next section we study ϕ -symmetric trans-Sasakian manifold with respect to quarter symmetric metric connection. Finally in section 6, we study locally concircular ϕ -symmetric trans-Sasakian manifold with respect to quarter symmetric metric connection.

2 Preliminaries

An $(2n + 1)$ dimensional Riemannian manifold (M, g) is called an almost Contact manifold [28] if there exists on M , a $(1, 1)$ tensor field ϕ , a vector field ξ and a 1-form η such that

$$\phi^2(X) = -X + \eta(X)\xi, \quad \eta(\phi X) = 0, \quad \phi\xi = 0, \quad \eta(\xi) = 1, \quad (2.1)$$

$$g(\phi X, \phi Y) = g(X, Y) - \eta(X)\eta(Y), \quad g(X, \xi) = \eta(X), \quad (2.2)$$

$$g(X, \phi Y) = -g(\phi X, Y), \quad (2.3)$$

for any vector fields X, Y on M .

An almost Contact metric structure (ϕ, ξ, η, g) on M is called a trans-Sasakian structure [1], if $(M \times R, J, G)$ belongs to the class W_4 [29], where J is the almost complex structure on $M \times R$ defined by $J(X, f \frac{d}{dt}) = (\phi X - f\xi, \eta(X) \frac{d}{dt})$ for any vector field X on M and smooth function f on $M \times R$. This may be expressed by the condition [30],

$$(\nabla_X \phi)(Y) = \alpha\{g(X, Y)\xi - \eta(Y)X\} + \beta\{g(\phi X, Y)\xi - \eta(Y)\phi X\}, \quad (2.4)$$

for some smooth functions α and β on M , and we say that the trans-Sasakian structure is of type (α, β) .

From (2.4), we have

$$(\nabla_X \xi) = -\alpha\phi X + \beta(X - \eta(X)\xi), \quad (2.5)$$

$$(\nabla_X \eta)(Y) = -\alpha g(\phi X, Y) + \beta g(\phi X, \phi Y). \quad (2.6)$$

In a 3-dimensional trans-Sasakian manifold, from (2.4), (2.5) and (2.6), we can derive [31]

$$R(X, Y)Z = \left[\frac{r}{2} + 2\xi\beta - 2(\alpha^2 - \beta^2)\right](g(Y, Z)X - g(X, Z)Y) \quad (2.7)$$

$$- g(Y, Z)\left[\left(\frac{r}{2} + \xi\beta - 3(\alpha^2 - \beta^2)\right)\eta(X)\xi\right. \\ \left. - \eta(X)(\phi \text{grad}\alpha - \text{grad}\beta) + (X\beta + (\phi X)\alpha)\xi\right]$$

$$+ g(X, Z)\left[\left(\frac{r}{2} + 2\xi\beta - 3(\alpha^2 - \beta^2)\right)\eta(Y)\xi\right. \\ \left. - \eta(Y)(\phi \text{grad}\alpha - \text{grad}\beta) + (Y\beta + (\phi Y)\alpha)\xi\right],$$

$$R(X, Y)\xi = (\alpha^2 - \beta^2)\{\eta(Y)X - \eta(X)Y\} \quad (2.8)$$

$$+ 2\alpha\beta\{\eta(Y)\phi X - \eta(X)\phi Y\} \\ + (Y\alpha)\phi X - (X\alpha)\phi Y + (Y\beta)\phi^2 X - (X\beta)\phi^2 Y,$$

$$S(X, \xi) = (2(\alpha^2 - \beta^2) - \xi\beta)\eta(X) - (\phi X)\alpha - X\beta. \quad (2.9)$$

When $\phi(\text{grad}\alpha) = \text{grad}\beta$, (2.9) reduces to

$$S(X, \xi) = 2(\alpha^2 - \beta^2)\eta(X). \quad (2.10)$$

Definition 2.1. A Riemannian manifold M is said to be locally symmetric if $\nabla R = 0$, where R is the Riemannian curvature tensor of M and ∇ is Levi-Civita connection of M .

3 Curvature Tensor of a Three Dimensional Trans-Sasakian Manifold with Respect to Quarter Symmetric Metric Connection

Let $\tilde{\nabla}$ be the linear connection and ∇ be the Riemannian connection of an almost Contact metric manifold such that

$$\tilde{\nabla}_X Y = \nabla_X Y + H(X, Y), \quad (3.1)$$

where H is the tensor field of type $(1, 1)$. For $\tilde{\nabla}$ to be quarter-symmetric metric connection on M , we have [12]

$$H(X, Y) = \frac{1}{2}[T(X, Y) + T'(X, Y) + T'(Y, X)], \quad (3.2)$$

$$g(T'(X, Y), Z) = g(T'(Z, X), Y). \quad (3.3)$$

In view of equation (1.2) and (3.3), we obtain

$$T'(X, Y) = g(\phi Y, X)\xi - \eta(X)\phi Y. \quad (3.4)$$

Using (1.2) and (3.4) in (3.2), we get

$$H(X, Y) = -\eta(X)\phi Y.$$

Hence a quarter symmetric metric connection in a trans-Sasakian manifold is given by

$$\tilde{\nabla}_X Y = \nabla_X Y - \eta(X)\phi Y. \quad (3.5)$$

This is the relation between quarter-symmetric metric connection and the Levi-Civita connection.

The curvature tensor \tilde{R} of M with respect to quarter symmetric metric connection $\tilde{\nabla}$ is defined by

$$\tilde{R}(X, Y)Z = \tilde{\nabla}_X \tilde{\nabla}_Y Z - \tilde{\nabla}_Y \tilde{\nabla}_X Z - \tilde{\nabla}_{[X, Y]} Z.$$

In view of (3.5), above equation takes the form

$$\begin{aligned} \tilde{R}(X, Y)Z &= R(X, Y)Z - 2\alpha g(\phi Y, X)\phi Z \\ &- [\alpha g(X, Z) + \beta g(\phi X, Z)]\eta(Y)\xi + [\alpha g(Y, Z) + \beta g(\phi Y, Z)]\eta(X)\xi \\ &+ (\alpha X + \beta \phi X)\eta(Y)\eta(Z) - (\alpha Y + \beta \phi Y)\eta(X)\eta(Z), \end{aligned} \quad (3.6)$$

where \tilde{R} and R are the Riemannian curvature tensor with respect to $\tilde{\nabla}$ and ∇ respectively. From equation (3.6) it follows that

$$\tilde{S}(Y, Z) = S(Y, Z) - \alpha g(Y, Z) + \beta g(\phi Y, Z) + 3\alpha \eta(Y)\eta(Z), \quad (3.7)$$

where \tilde{S} and S are the Ricci tensor of the connections $\tilde{\nabla}$ and ∇ respectively. Contracting (3.7), we get

$$\tilde{r} = r, \quad (3.8)$$

where \tilde{r} and r are the scalar curvature of the connections $\tilde{\nabla}$ and ∇ respectively.

4 Locally ϕ -symmetric Trans-Sasakian Manifold with Respect to Quarter Symmetric Metric Connection

Definition 4.1. A trans-Sasakian manifold M is said to be locally ϕ -symmetric if

$$\phi^2((\nabla_W R)(X, Y)Z) = 0, \quad (4.1)$$

for any arbitrary vector fields X, Y, Z, W orthogonal to ξ .

Analogous to this definition, we define a locally ϕ -symmetric trans-Sasakian manifold with respect to the quarter-symmetric metric connection by

$$\phi^2((\tilde{\nabla}_W \tilde{R})(X, Y)Z) = 0, \quad (4.2)$$

for all vector fields X, Y, Z and W orthogonal to ξ .

Using (3.5), we can write

$$(\tilde{\nabla}_W \tilde{R})(X, Y)Z = (\nabla_W R)(X, Y)Z - \eta(W)\phi \tilde{R}(X, Y)Z. \quad (4.3)$$

Now differentiating (3.6) with respect to W and using (2.4) and (2.6), we obtain

$$\begin{aligned}
 (\nabla_W \tilde{R})(X, Y)Z &= (\nabla_W R)(X, Y)Z & (4.4) \\
 &- 2\alpha g(\phi Y, X)[\alpha(g(W, Z)\xi - \eta(Z)W) + \beta(g(\phi W, Z)\xi \\
 &- \eta(Z)\phi W)] - [\alpha g(X, Z) + \beta g(\phi X, Z)][\{-\alpha g(\phi W, Y) \\
 &+ \beta g(\phi W, \phi Y)\}\xi + \eta(Y)\{-\alpha\phi W + \beta(W - \eta(W)\xi)\}] \\
 &+ [\alpha g(Y, Z) + \beta g(\phi Y, Z)][\{-\alpha g(\phi W, X) + \beta g(\phi W, \phi X)\}\xi \\
 &+ \eta(X)\{-\alpha\phi W + \beta(W - \eta(W)\xi)\}] \\
 &+ (\alpha X + \beta\phi X)[\{-\alpha g(\phi W, Y) + \beta g(\phi W, \phi Y)\}\eta(Z) \\
 &+ \eta(Y)\{-\alpha g(\phi W, Z) + \beta g(\phi W, \phi Z)\}] + \beta[\alpha(g(W, X)\xi \\
 &- \eta(X)W) + \beta(g(\phi W, X)\xi - \eta(X)\phi W)]\eta(Y)\eta(Z) \\
 &- (\alpha Y + \beta\phi Y)[\{-\alpha g(\phi W, X) + \beta g(\phi W, \phi X)\}\eta(Z) \\
 &+ \eta(X)\{-\alpha g(\phi W, Z) + \beta g(\phi W, \phi Z)\}] - \beta[\alpha(g(W, Y)\xi \\
 &- \eta(Y)W) + \beta(g(\phi W, Y)\xi - \eta(Y)\phi W)]\eta(X)\eta(Z).
 \end{aligned}$$

Using (2.1) and (4.4) in (4.3) and applying ϕ^2 , we get

$$\begin{aligned}
 \phi^2((\tilde{\nabla}_W \tilde{R})(X, Y)Z) &= \phi^2((\nabla_W R)(X, Y)Z) & (4.5) \\
 &+ 2\alpha g(\phi Y, X)[\alpha\phi^2 W + \beta\phi^2(\phi W)]\eta(Z) \\
 &- \eta(Y)[\alpha g(X, Z) + \beta g(\phi X, Z)][\{-\alpha\phi^2(\phi W) + \beta\phi^2 W \\
 &+ \eta(X)[\alpha g(Y, Z) + \beta g(\phi Y, Z)][\{-\alpha\phi^2(\phi W) + \beta\phi^2 W \\
 &+ (\alpha\phi^2 X + \beta\phi^2(\phi X))[\{-\alpha g(\phi W, Y) + \beta g(\phi W, \phi Y)\}\eta(Z) \\
 &+ \eta(Y)\{-\alpha g(\phi W, Z) + \beta g(\phi W, \phi Z)\}] \\
 &- (\alpha\phi^2 Y + \beta\phi^2(\phi Y))[\{-\alpha g(\phi W, X) + \beta g(\phi W, \phi X)\}\eta(Z) \\
 &+ \eta(X)\{-\alpha g(\phi W, Z) + \beta g(\phi W, \phi Z)\}] \\
 &- \eta(W)\phi^2(\phi(\tilde{R}(X, Y)Z)).
 \end{aligned}$$

If we consider X, Y, Z and W orthogonal to ξ then (4.5) reduces to

$$\phi^2((\tilde{\nabla}_W \tilde{R})(X, Y)Z) = \phi^2((\nabla_W R)(X, Y)Z). \quad (4.6)$$

Hence we can state:

Theorem 4.1. *In a three dimensional trans-Sasakian manifold, the locally ϕ -symmetric remains invariant under quarter-symmetric metric connection $\tilde{\nabla}$ and Levi-Civita connection ∇ .*

5 ϕ -Symmetric Trans-Sasakian Manifold with Respect to the Quarter-Symmetric Metric Connection

Definition 5.1. A trans-Sasakian manifold M is said to be ϕ -symmetric if

$$\phi^2((\nabla_W R)(X, Y)Z) = 0, \quad (5.1)$$

for any arbitrary vector fields X, Y, Z and W on M .

Similarly, a trans-Sasakian manifold M is said to be ϕ -symmetric with respect to the quarter-symmetric metric connection if

$$\phi^2((\tilde{\nabla}_W \tilde{R})(X, Y)Z) = 0, \quad (5.2)$$

for arbitrary vector fields X, Y, Z and W .

Now by virtue of (2.1), (5.2) gives

$$- (\tilde{\nabla}_W \tilde{R})(X, Y)Z + \eta((\tilde{\nabla}_W \tilde{R})(X, Y)Z)\xi = 0, \tag{5.3}$$

from which it follows that

$$- g((\tilde{\nabla}_W \tilde{R})(X, Y)Z, U) + \eta((\tilde{\nabla}_W \tilde{R})(X, Y)Z)\eta(U) = 0. \tag{5.4}$$

Let $\{e_i\}, i = 1, 2, 3$ be an orthonormal basis of the tangent space at any point of the space form. Then putting $X = U = e_i$, in (5.4) and taking summation over $i, 1 \leq i \leq 3$, we get

$$- (\tilde{\nabla}_W \tilde{S})(Y, Z) + \sum \eta((\tilde{\nabla}_W \tilde{R})(e_i, Y)Z)\eta(e_i) = 0. \tag{5.5}$$

The second term of (5.5) by putting $Z = \xi$ takes the form

$$\eta((\tilde{\nabla}_W \tilde{R})(e_i, Y)\xi)\eta(e_i) = g((\tilde{\nabla}_W \tilde{R})(e_i, Y)\xi, \xi)g(e_i, \xi). \tag{5.6}$$

By using (3.5) and (4.3), we get

$$g((\tilde{\nabla}_W \tilde{R})(e_i, Y)\xi, \xi) = g((\nabla_W \tilde{R})(e_i, Y)\xi, \xi) - \eta(W)\eta(\phi \tilde{R}(e_i, Y)\xi). \tag{5.7}$$

On simplification we obtain from (5.7) that

$$g((\tilde{\nabla}_W \tilde{R})(e_i, Y)\xi, \xi) = g((\nabla_W R)(e_i, Y)\xi, \xi). \tag{5.8}$$

In a trans-Sasakian manifold M , we have $g((\nabla_W R)(e_i, Y)\xi, \xi) = 0$ and so from (5.8), we have

$$g((\tilde{\nabla}_W \tilde{R})(e_i, Y)\xi, \xi) = 0. \tag{5.9}$$

By replacing Z by ξ in (5.5) and using (5.9), we get

$$(\tilde{\nabla}_W \tilde{S})(Y, \xi) = 0. \tag{5.10}$$

We know that

$$(\tilde{\nabla}_W \tilde{S})(Y, \xi) = \tilde{\nabla}_W \tilde{S}(Y, \xi) - \tilde{S}(\tilde{\nabla}_W Y, \xi) - \tilde{S}(Y, \tilde{\nabla}_W \xi). \tag{5.11}$$

By making use of (2.4), (2.9), (3.5) and (3.7) in (5.11), we get

$$\begin{aligned} \beta S(Y, W) - \alpha S(Y, \phi W) &= 2(\alpha^2 - \beta^2 + \alpha)[- \alpha g(Y, \phi W) + \beta g(\phi Y, \phi W)] \\ &- (\alpha^2 - \beta^2)g(Y, \phi W) + 2\alpha\beta g(\phi Y, \phi W) \\ &+ 2\beta(\alpha^2 - \beta^2)\eta(W)\eta(Y). \end{aligned} \tag{5.12}$$

Replacing Y by ϕY and W by ϕW , we get

$$\begin{aligned} &\beta[S(Y, W) - 2(\alpha^2 - \beta^2 + \alpha)g(Y, W) + 2\alpha\eta(Y)\eta(W) + \beta g(W, \phi Y) - \alpha g(\phi Y, \phi W)] \\ &+ \alpha[S(\phi Y, W) - 2(\alpha^2 - \beta^2 + \alpha)g(\phi Y, W) - \beta g(\phi W, \phi Y) - \alpha g(\phi Y, W)] = 0. \end{aligned}$$

This implies

$$\begin{aligned} &S(Y, W) - 2(\alpha^2 - \beta^2 + \alpha)g(Y, W) + 2\alpha\eta(Y)\eta(W) + \beta g(W, \phi Y) \\ &- \alpha g(\phi Y, \phi W) = 0 \end{aligned} \tag{5.13}$$

and

$$S(\phi Y, W) - 2(\alpha^2 - \beta^2 + \alpha)g(\phi Y, W) - \beta g(\phi W, \phi Y) - \alpha g(\phi Y, W) = 0. \tag{5.14}$$

Contracting (5.13) and (5.14), we get

$$r = 6(\alpha^2 - \beta^2 + \alpha). \tag{5.15}$$

Therefore we can state,

Theorem 5.1. Let M be a three dimensional ϕ -symmetric trans-Sasakian manifold with respect to quarter symmetric metric connection $\tilde{\nabla}$. Then the manifold has a scalar curvature r with respect to Levi-Civita connection ∇ of M given by (5.15).

Case I: Considering $\alpha = 1$ and $\beta = 0$ in (5.15) we get $r = 12$ which is proved by Pradeep Kumar K. T., Bagewadi C. S. and Venkatesha in [21] for a Sasakian manifold.

Case II: And considering $\alpha = 0$ and $\beta = 1$ in (5.15) we get $r = -6$ which is proved by Prakasha D. G. in [23] for a Kenmotsu manifold.

6 Locally Concircular ϕ -symmetric Trans-Sasakian Manifold with Respect to Quarter Symmetric Metric Connection

Definition 6.1. A trans-Sasakian manifold M is said to be locally concircular ϕ -symmetric if

$$\phi^2((\nabla_W \tilde{C})(X, Y)Z) = 0, \quad (6.1)$$

for any arbitrary vector fields X, Y, Z, W orthogonal to ξ , where \tilde{C} is the concircular curvature tensor given by [32].

$$\tilde{C}(X, Y)Z = R(X, Y)Z - \frac{r}{6}[g(Y, Z)X - g(X, Z)Y]. \quad (6.2)$$

A trans-Sasakian manifold M is said to be locally concircular ϕ -symmetric with respect to the quarter-symmetric metric connection if

$$\phi^2((\tilde{\nabla}_W \tilde{\tilde{C}})(X, Y)Z) = 0. \quad (6.3)$$

for all vector field X, Y, Z and W orthogonal to ξ , where $\tilde{\tilde{C}}$ is the concircular curvature tensor with respect to quarter symmetric metric connection given by

$$\tilde{\tilde{C}}(X, Y)Z = \tilde{R}(X, Y)Z - \frac{\tilde{r}}{6}[g(Y, Z)X - g(X, Z)Y], \quad (6.4)$$

where \tilde{R} and \tilde{r} are the Riemannian curvature tensor and the scalar curvature with respect to quarter symmetric metric connection.

Using (3.5), we can write

$$(\tilde{\nabla}_W \tilde{\tilde{C}})(X, Y)Z = (\nabla_W \tilde{\tilde{C}})(X, Y)Z - \eta(W)\phi\tilde{\tilde{C}}(X, Y)Z. \quad (6.5)$$

Now differentiating (6.4) covariantly with respect to W , we obtain

$$(\tilde{\nabla}_W \tilde{\tilde{C}})(X, Y)Z = (\nabla_W \tilde{R})(X, Y)Z - \frac{\nabla_W \tilde{r}}{6}[g(Y, Z)X - g(X, Z)Y]. \quad (6.6)$$

Using (3.8) and (4.4) in (6.6), we have

$$\begin{aligned}
 (\nabla_w \tilde{\tilde{C}})(X, Y)Z &= (\nabla_w R)(X, Y)Z - 2\alpha g(\phi Y, X)[\alpha(g(W, Z)\xi \\
 &- \eta(Z)W) + \beta(g(\phi W, Z)\xi - \eta(Z)\phi W)] \\
 &- [\alpha g(X, Z) + \beta g(\phi X, Z)][\{-\alpha g(\phi W, Y) \\
 &+ \beta g(\phi W, \phi Y)\}\xi + \eta(Y)\{-\alpha\phi W + \beta(W - \eta(W)\xi)\}] \\
 &+ [\alpha g(Y, Z) + \beta g(\phi Y, Z)][\{-\alpha g(\phi W, X) \\
 &+ \beta g(\phi W, \phi X)\}\xi + \eta(X)\{-\alpha\phi W + \beta(W - \eta(W)\xi)\}] \\
 &+ (\alpha X + \beta\phi X)[\{-\alpha g(\phi W, Y) + \beta g(\phi W, \phi Y)\}\eta(Z) \\
 &+ \eta(Y)\{-\alpha g(\phi W, Z) + \beta g(\phi W, \phi Z)\}] + \beta[\alpha(g(W, X)\xi \\
 &- \eta(X)W) + \beta(g(\phi W, X)\xi - \eta(X)\phi W)]\eta(Y)\eta(Z) \\
 &- (\alpha Y + \beta\phi Y)[\{-\alpha g(\phi W, X) + \beta g(\phi W, \phi X)\}\eta(Z) \\
 &+ \eta(X)\{-\alpha g(\phi W, Z) + \beta g(\phi W, \phi Z)\}] - \beta[\alpha(g(W, Y)\xi \\
 &- \eta(Y)W) + \beta(g(\phi W, Y)\xi - \eta(Y)\phi W)]\eta(X)\eta(Z) \\
 &- \frac{\nabla_w \tilde{r}}{6}[g(Y, Z)X - g(X, Z)Y].
 \end{aligned} \tag{6.7}$$

Again using (6.2), the equation (6.7) reduces to

$$\begin{aligned}
 (\nabla_w \tilde{\tilde{C}})(X, Y)Z &= (\nabla_w C)(X, Y)Z - 2\alpha g(\phi Y, X)[\alpha(g(W, Z)\xi \\
 &- \eta(Z)W) + \beta(g(\phi W, Z)\xi - \eta(Z)\phi W)] \\
 &- [\alpha g(X, Z) + \beta g(\phi X, Z)][\{-\alpha g(\phi W, Y) \\
 &+ \beta g(\phi W, \phi Y)\}\xi + \eta(Y)\{-\alpha\phi W + \beta(W - \eta(W)\xi)\}] \\
 &+ [\alpha g(Y, Z) + \beta g(\phi Y, Z)][\{-\alpha g(\phi W, X) \\
 &+ \beta g(\phi W, \phi X)\}\xi + \eta(X)\{-\alpha\phi W + \beta(W - \eta(W)\xi)\}] \\
 &+ (\alpha X + \beta\phi X)[\{-\alpha g(\phi W, Y) + \beta g(\phi W, \phi Y)\}\eta(Z) \\
 &+ \eta(Y)\{-\alpha g(\phi W, Z) + \beta g(\phi W, \phi Z)\}] + \beta[\alpha(g(W, X)\xi \\
 &- \eta(X)W) + \beta(g(\phi W, X)\xi - \eta(X)\phi W)]\eta(Y)\eta(Z) \\
 &- (\alpha Y + \beta\phi Y)[\{-\alpha g(\phi W, X) + \beta g(\phi W, \phi X)\}\eta(Z) \\
 &+ \eta(X)\{-\alpha g(\phi W, Z) + \beta g(\phi W, \phi Z)\}] - \beta[\alpha(g(W, Y)\xi \\
 &- \eta(Y)W) + \beta(g(\phi W, Y)\xi - \eta(Y)\phi W)]\eta(X)\eta(Z).
 \end{aligned} \tag{6.8}$$

Using (2.1) and (6.8) in (6.5) and applying ϕ^2 , we get

$$\begin{aligned}
 \phi^2(\tilde{\nabla}_w \tilde{\tilde{C}})(X, Y)Z &= \phi^2((\nabla_w \tilde{\tilde{C}})(X, Y)Z) + 2\alpha g(\phi Y, X)[\alpha\phi^2 W + \beta\phi^2(\phi W)]\eta(Z) \\
 &- \eta(Y)[\alpha g(X, Z) + \beta g(\phi X, Z)][-\alpha\phi^2(\phi W) + \beta\phi^2 W] \\
 &+ \eta(X)[\alpha g(Y, Z) + \beta g(\phi Y, Z)][-\alpha\phi^2(\phi W) + \beta\phi^2 W] \\
 &+ (\alpha\phi^2 X + \beta\phi^2(\phi X))[\{-\alpha g(\phi W, Y) + \beta g(\phi W, \phi Y)\}\eta(Z) \\
 &+ \eta(Y)\{-\alpha g(\phi W, Z) + \beta g(\phi W, \phi Z)\}] \\
 &- (\alpha\phi^2 Y + \beta\phi^2(\phi Y))[\{-\alpha g(\phi W, X) + \beta g(\phi W, \phi X)\}\eta(Z) \\
 &+ \eta(X)\{-\alpha g(\phi W, Z) + \beta g(\phi W, \phi Z)\}] \\
 &- \eta(W)\phi^2(\phi(\tilde{\tilde{C}}(X, Y)Z)).
 \end{aligned} \tag{6.9}$$

If we consider X, Y, Z and W orthogonal to ξ , then (6.9) reduces to

$$\phi^2(\tilde{\nabla}_w \tilde{\tilde{C}})(X, Y)Z = \phi^2((\nabla_w \tilde{\tilde{C}})(X, Y)Z). \tag{6.10}$$

Hence we state:

Theorem 6.1. *In a three dimensional trans-Sasakian manifold, locally concircular ϕ -symmetric remains invariant under quarter symmetric metric $\tilde{\nabla}$ and Levi-Civita connection ∇ .*

In view of (2.1) and (6.7), we have from (6.5) that

$$\begin{aligned} \phi^2(\tilde{\nabla}_W \tilde{C})(X, Y)Z &= \phi^2((\nabla_W R)(X, Y)Z) + 2\alpha g(\phi Y, X)[\alpha\phi^2 W + \beta\phi^2(\phi W)]\eta(Z) \quad (6.11) \\ &- \eta(Y)[\alpha g(X, Z) + \beta g(\phi X, Z)][-\alpha\phi^2(\phi W) + \beta\phi^2 W] \\ &+ \eta(X)[\alpha g(Y, Z) + \beta g(\phi Y, Z)][-\alpha\phi^2(\phi W) + \beta\phi^2 W] \\ &+ (\alpha\phi^2 X + \beta\phi^2(\phi X))\{-\alpha g(\phi W, Y) + \beta g(\phi W, \phi Y)\}\eta(Z) \\ &+ \eta(Y)\{-\alpha g(\phi W, Z) + \beta g(\phi W, \phi Z)\} \\ &- (\alpha\phi^2 Y + \beta\phi^2(\phi Y))\{-\alpha g(\phi W, X) + \beta g(\phi W, \phi X)\}\eta(Z) \\ &+ \eta(X)\{-\alpha g(\phi W, Z) + \beta g(\phi W, \phi Z)\} \\ &- \eta(W)\phi^2(\phi(\tilde{C})(X, Y)Z) \\ &- \frac{\nabla_W \tilde{r}}{6}[g(Y, Z)\phi^2 X - g(X, Z)\phi^2 Y]. \end{aligned}$$

If we consider X, Y, Z and W orthogonal to ξ , then (6.11) reduces to

$$\begin{aligned} \phi^2(\tilde{\nabla}_W \tilde{C})(X, Y)Z &= \phi^2((\nabla_W R)(X, Y)Z) \quad (6.12) \\ &- \frac{\nabla_W \tilde{r}}{6}[g(Y, Z)\phi^2 X - g(X, Z)\phi^2 Y]. \end{aligned}$$

If r is constant, then $\nabla_W r = 0$. Therefore (6.12) yields

$$\phi^2(\tilde{\nabla}_W \tilde{C})(X, Y)Z = \phi^2((\nabla_W R)(X, Y)Z). \quad (6.13)$$

Hence we state:

Theorem 6.2. *A three dimensional locally concircular ϕ -symmetric trans-Sasakian manifold admitting quarter symmetric metric connection is locally ϕ -symmetric if and only if the scalar curvature r is constant with respect to Levi-Civita connection.*

Competing Interests

The authors declare that no competing interests exist.

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